

Crop Map of England

Product Specification- v.2018.2

**Non-Sensitive
Information**

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Abbreviations

CROME – Crop Map of England

ESA – European Space Agency

GRD – Ground Range Detected

LUCODE – Land Use Code

SNAP – Sentinel Application Platform

VH – Vertical-Horizontal Polarisation

VV – Vertical-Vertical Polarisation

VV/VH – Vertical-Vertical/Vertical-Horizontal dual Polarisation

1 Introduction

1.1 Document Control

1.1.1 Revision History

Date	Author	Version	Change reference
16/11/2017	Sanjay Rana	0.9	V0.8 revised to include new LUCODES and Labels, also information on 2017.2 ground truth.
12/12/2018	Sanjay Rana	0.10	V.09 revised to include confusion matrix for CROME 2018.2, revised methodology

1.1.2 Reviewers and Contributors

Name	Role	Team
Sanjay Rana	Lead Author	GI Tech Team
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1.2 Purpose Scope

This document defines the product specification for the Crop Map of England (CROME) layer delivered by the Rural Payments Agency (RPA).

CROME is a tessellated multi-temporal visualisation of the type and distribution of land covers identified using remote sensing techniques. The purpose of this specification is to define that representation plus the technical details for the reference dataset structure, data format and delivery. This document includes the technical specification and a general overview of the methodology used to produce the CROME layer.

The CROME layer covers most of the land in England (including some small isles) into approximately 32 million hexagon cells. The CROME Layer is expected to be revised once a year during September-October, and then released as soon as after.

It is important to note here that CROME is basically a scientific product and not a conventional cartographic product. Therefore, minimal efforts have been taken to generalise the thematic variation of crop and land cover types to revise the land use types to homogenise land cover over an area and to improve the cosmetic appearance of the layer.

1.3 Document Ownership and Distribution

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1.4 Assumptions, Dependencies and Constraints

The document describes the derivation of a technical geospatial data product. It is not written for the layman and thus assumes that users of this document are knowledgeable in:

- Geographic Information Systems
- Earth Observation concepts

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2 Data Creation

2.1 Feature Classification

The main sources for crop classification are satellite images from the Sentinel constellation together with Ground Truth data for land cover types. A combination of radar and multispectral imagery from Sentinel sensors was used for automatic classification. Sentinel-1 transmits and receives microwave radiation in the horizontal (H) and vertical (V) polarisation. Sentinel-2 captures multispectral imagery in 13 spectral bands at varying spatial resolutions. More information regarding the specification of each satellite can be found on the [ESA website](#).

2.2 Geometry

Unlike conventional land cover classification maps, the classification of crops and land cover in CROME is represented as hexagon cells. Traditional thematic visualisation of geospatial information (e.g. distribution of crop types and other land use types) partitions the land into either a regular grid (e.g. [CropScape-Cropland Data layer](#)) or an agricultural/administrative polygonal representation of the land use extent (e.g. [CEH Land Cover plus –Crops 2015](#); [onesoil.ai](#)). However, the CROME layer is based on the hexagonal grid, which provides a superior opportunity to model and visualise the arbitrary arrangement of land use forms and locations in comparison to a regular grid. Furthermore, it is better than the agricultural/administrative polygonal representation because it doesn't rely on any third party vector product, which are often needed to create a good quality polygonal representation.

Each hexagon cell covers an area of 4156 sq. m., or 0.41 hectares. The hexagon cells in the CROME layer are spatially distinct units and the CROME layer doesn't provide any spatial adjacency information. The vertices of adjacent cells are mostly coincident; therefore the CROME layer provides a continuous representation of the land use. The hexagon cells are not constrained by any topographic features, except the extent of the land.



Figure 1. Example of CROME hexagonal classification cells

2.3 Attributes

In the creation of the CROME layer, attribution is generated from the associated imagery and the feature classification process.

3 Reference Layer Features

3.1 Representation

The classification is provided as hexagonal polygon cells, with each cell being attributed a land cover classification, according to the classification in Annex A. An example of the landscape and the classification cells, labelled with the land cover code in Annex A, is shown in Figure 1.

Unlike previous versions, versions CROME 2018 data production didn't involve any climate zones as internal experiments revealed that Random Forest Classification performed with just as much accuracy with or without regional labelling. The distribution has also been revised to be now based on ceremonial counties because user feedback have suggested that zones used in previous versions were too large. The ceremonial county boundaries are based on the boundary line product by the OS ([link](#)). CROME 2018 is distributed on 48 ceremonial counties. Table 1 lists the number of counties and their respective codes and Figure 2 shows the map of the counties.

Ceremonial County	County Code		Ceremonial County	County Code
Bedfordshire	BED		North Yorkshire	NYO
Berkshire	BER		Oxfordshire	OXF
Buckinghamshire	BUC		Rutland	RUT
Cambridgeshire	CAM		Shropshire	SHR
Cheshire	CHE		Bristol and Somerset	BRS
Cumbria	CMB		Staffordshire	STF
Cornwall	COR		Suffolk	SUF
Derbyshire	DER		Surrey	SUR
Devon	DEV		South Yorkshire	SYO
Dorset	DOR		Tyne & Wear	TAW
Durham	DUR		Warwickshire	WAR
East Riding of Yorkshire	ERY		Wiltshire	WIL
Essex	ESS		West Midlands	WMD
East Sussex	ESX		Worcestershire	WOR
Gloucestershire	GLO		West Sussex	WSX
Greater Manchester	GMN		West Yorkshire	WYR
Hampshire	HAM		Northamptonshire	NRM
Herefordshire	HER		Northumberland	NRT
Hertfordshire	HRT		North Yorkshire	NYO
Isle of Wight	IOW		Oxfordshire	OXF
Kent	KEN		Rutland	RUT
Lancashire	LAN		Shropshire	SHR
Leicestershire	LEI		Somerset	SOM
Lincolnshire	LIN		Staffordshire	STF
City and Greater London	LON		Suffolk	SUF
Merseyside	MER		Surrey	SUR
Norfolk	NOR		South Yorkshire	SYO
Nottinghamshire	NOT		Tyne & Wear	TAW
Northamptonshire	NRM			
Northumberland	NRT			

Table 1. CROME data distribution zones with their zone codes and cell counts respectively.

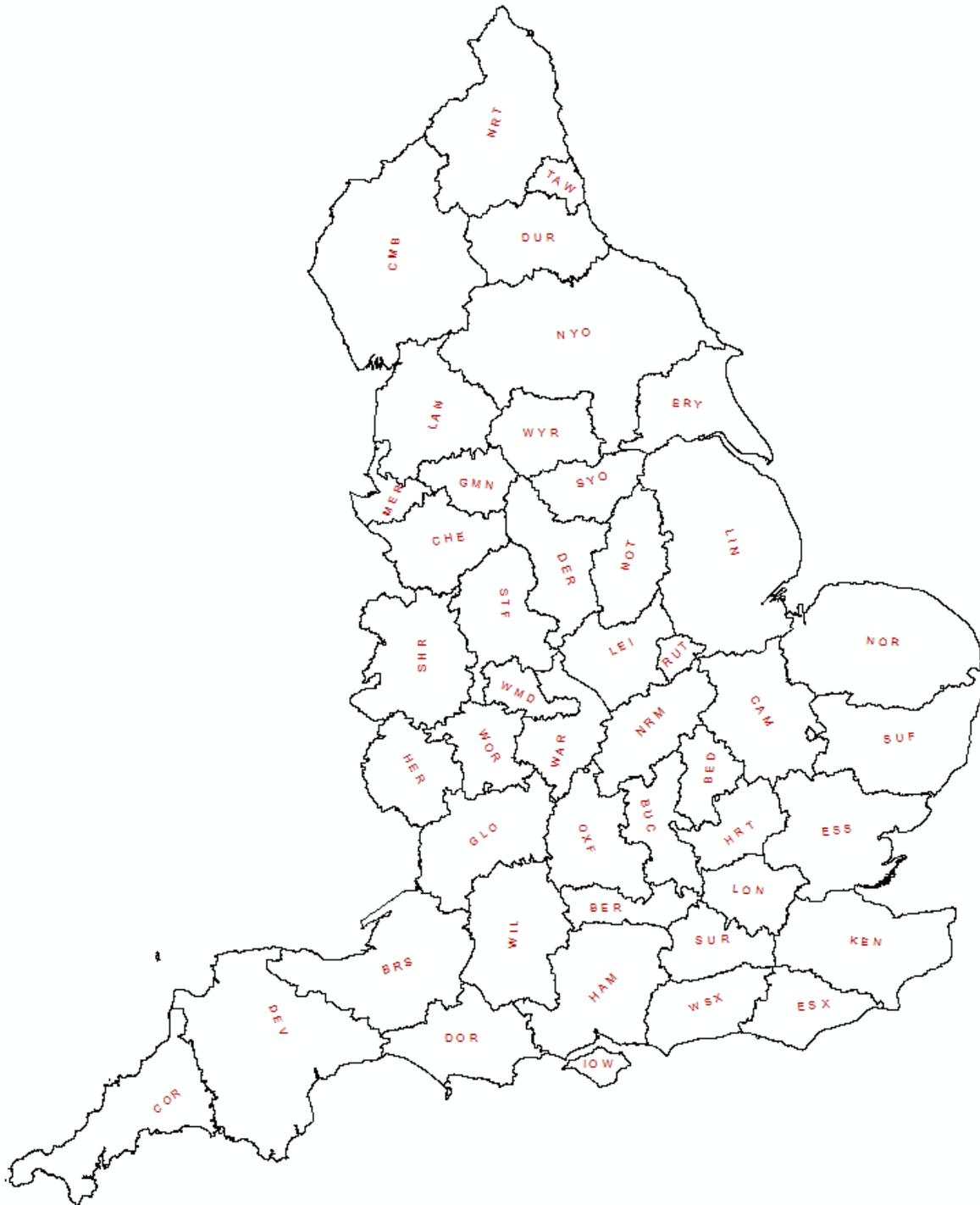


Figure 2. Ordnance Survey Ceremonial Counties in England (source: Ordnance Survey). See Table 1 for full names for each county codes.

4 CROME Classification

The classification of the topography was performed using Random Forest classification, a supervised machine learning approach. More information on Random Forest Classification can be found on the authors' [homepage](#). The approach learns the classification of specific crop types by associating backscatter characteristics of each radar polarisation (VV, VH, VV/VH) to known land covers, previously collected by field inspectors. The ground truth points and radar images were fed into the workflow, outlined in Figure 3, making up the four main work packages described below in further detail.

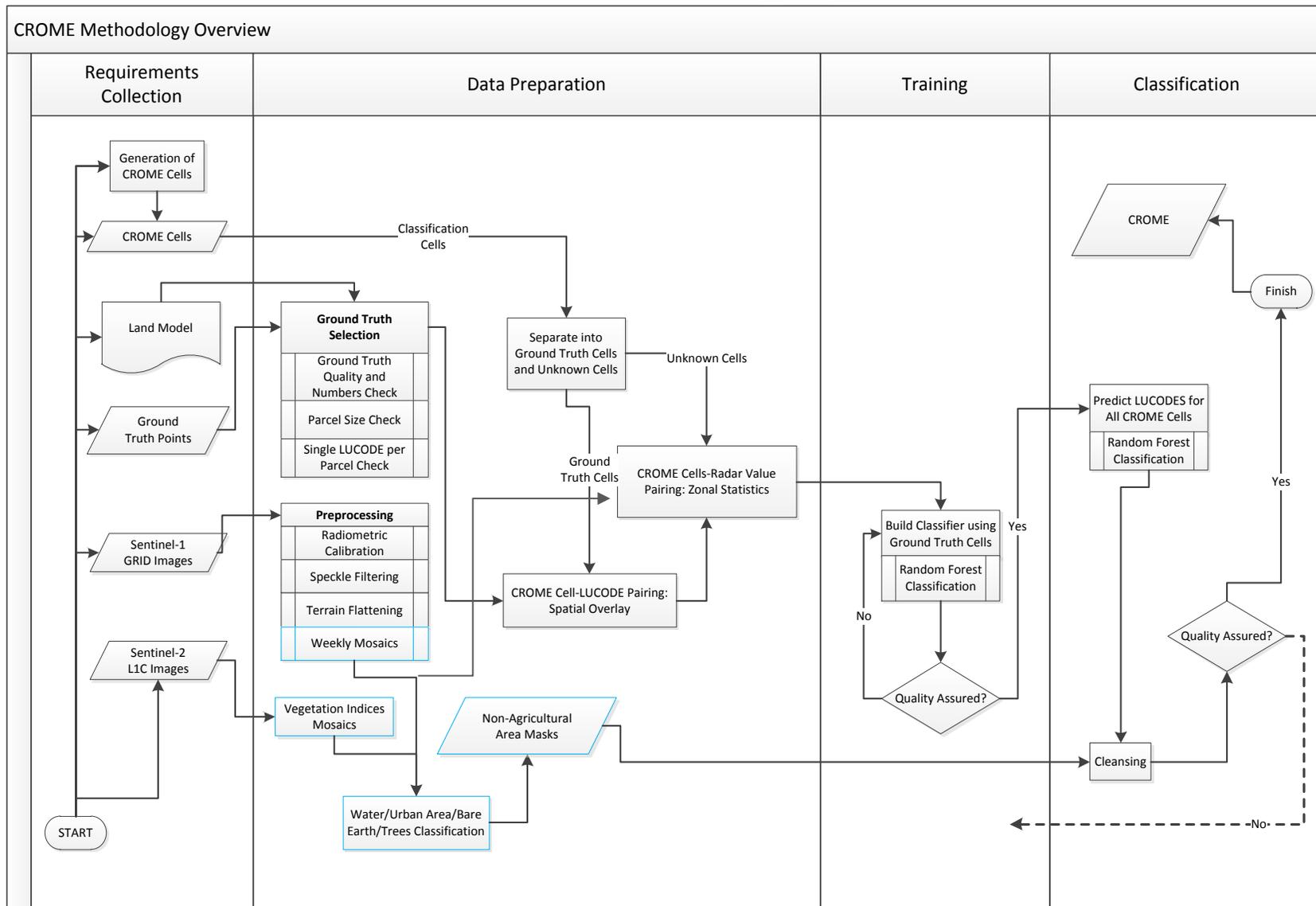


Figure 3. Workflow for CROME classification

4.1 Requirements Collection

This step involves the creation and collection of the input datasets and specifications required to perform the classification. The step involves four main inputs:

- a) CROME Cells: These are hexagon cells that form the spatial framework of the CROME layer. These are essentially Voronoi polygons and were created using a combination of ESRI ArcMap and FME applications.
- b) Land Model (current version 1.7.1): This is an internal RPA document that contains a list and specification of the relevant land cover and crop types which are eventually assigned to the CROME cells.
- c) Ground Truth Points: These are a record of the spatial location and type of crop and land use found by the RPA field inspectors during late-spring and summer period of 2018. The ground truth collection process involves verification and, where required, correction of the crop and other land cover types declared by the farmers against each parcel registered under their name. In order to minimise classification errors, only the ground truth data and parcels that matched the following conditions were used:
 - a. Parcels only contained a single crop/land use type.
 - b. Parcel area after applying a negative buffer of 20 m (to exclude contamination from hedges and other boundary features) was greater than 0.32 ha (i.e. it would cover 80% of a CROME cell area).
 - c. The crop/land use type was present in at least 10 ground truth parcels.

In addition, the numbers and varieties for non-agricultural areas were boosted by collecting additional ground truth information, such as man-made surfaces and structures, from other RPA datasets e.g. inspections. A total of 27927 ground truth samples (i.e. CROME cells with associated with ground truth labels used for Training) were used for building the Random Forest classifier.

- d) Sentinel-1 GRD images: These are Sentinel-1 Radar Ground Range Detected (GRD) dual polarisation (VV/VH) images for the period of January till September 2018, covering the main land masses of England. A total of 1660 scenes were used. These can be downloaded from the scihub (scihub.copernicus.eu) or Alaska Satellite Data Facility.
- e) Sentinel-2 Level1C images: These are Sentinel-2 Optical images for the period of May till June 2018. These can be downloaded from the scihub (scihub.copernicus.eu).

4.2 Data Preparation

The objective of this step is to attribute the CROME Cells with the required LUCODE (only for cells used during supervised training) and radar values for the purposes of classification. It involves the following main processes:

- a) Ground truth data points are filtered by applying a combination of simple attribute and spatial filtering using farm field polygons.
- b) The Sentinel-1 GRD images are processed using the Sentinel Application Platform (more information available on [SNAP](#) homepage) software to transform the raw images into georeferenced and radiometrically corrected Sigma-0 (backscattering coefficient) images.
- c) “Zonal Statistics” analysis is performed to calculate the weekly mean of VV, VH and VV/VH-ratio image values for the area covered by each CROME cell. Each CROME cell (32 million in total) is assigned a pair of triplet values i.e. mean VV, VH and VV/VH, and VV, VH, VV/VH standard deviation based on an England-wide weekly composite of scenes. Statistics were calculated of each polarization combinations (VV, VH and VV/VH) from suitable 156 weekly

mosaics radar scenes captured from January to September 2018, (totaling 1660 images). Weekly statistics allowed a common temporal reference axis for all cells because although satellite pass dates over cells are broadly predictable as per ESA guidance, i.e. within 5-10 days revisit, these still varied considerably across England thereby creating data gaps.

- d) Spatial overlap is tested between the selected ground truth subset points and all the CROME cell polygons to assign the known LUCODES to the training-CROME cell polygons.

Classification rules were formulated based on the known LUCODES, established in step (d), and the monthly radar backscattering coefficient values derived in step (c) from the training CROME cells.

4.3 Training

The objective of this step is to automatically build the classification rules that can be used to predict the LUCODE of a CROME cell, given its associated monthly radar backscattering coefficient values.

This work uses the Random Forest classification technique, a supervised machine learning approach, available in the R application. The unique advantage of Random Forest classification is that given a large number of ground truth points, it is able to perform robust cross-validation internally by generating numerous decision trees.

The training process involves randomly combining input variables and deriving a permutation of input variables that provides the most instances of accurate match between the known LUCODE and a predicted LUCODE. The software internally uses 2/3rds of the input variables for developing and training the ruleset, and the remaining 1/3rd for testing the classification.

4.4 Classification

Each CROME cell is then applied a LUCODE from the Random Forest classification ruleset. A random visual check using 2018 Sentinel-2 images was performed to detect obvious misclassifications. Simple cases of misclassifications (e.g. slightly rough areas of manmade surfaces conflicted with grass, water, urban areas misclassified as trees, and vice versa) were corrected by calculating normalized difference vegetation index, Modified Soil Adjusted Vegetation Index, Visible Atmospherically Resistant Index, Greenness Index, and Blueness Index.

5 Features Types and Attribution

5.1 Attribution

Table 2 shows the attribute for each CROME cell:

Name	Type	Properties	Comments
CROMEID	TEXT	Primary Key	Unique across all supply years
REFDATE	NUMBER	Not Null	The date of the classification was performed.
LUCODE	TEXT	Not Null	The land use code. See Annex A for lookup tables.
SHAPE	GEOMETRY	Not Null	Polygon representing the extent of the classified land use object.

Table 2. Attribute Schema of CROME layer

5.1.1 CROMEID

The CROMEID is the unique identifier assigned to each cell, consisting of the letters 'RPA' and a twelve digit number, which are the Easting and Northing coordinates of the centroid of the cell.

5.1.2 REFDATE

The REFDATE is the date or date range of the images referenced to assign the land use code to the CROME cell. The date format used is YYYYMMDD e.g. 20181121. The value is expected to remain constant for each cell in a CROME release.

5.1.3 LUCODE

The Land Use Code is alphanumeric code of up to 5 characters long, and is intended to record land use information. At present, all non-agricultural areas will be assigned a generic non-agricultural land use code. These land use codes are based on the land model used by the RPA as part of the claim purpose. The table in Annex A contains the valid Land Use Code (Column 3) that will be used in the current release of the CROME.

5.2 Data Format and Naming

The dataset is supplied in the ESRI shapefile format, together with a valid projection file (*.prj) that defines the coordinate system as British National Grid. The data for a given year shall be supplied either as a single shapefile or as a series of shapefiles that collectively cover all CROME zones.

The dataset format shall be consistent with the specification in Section 5.1, with all fields whose source is marked as shapefile being included in the supplied dataset.

The shapefile name shall be as follows:

CROME_<YYYYMMDD>_<ZONECODE>.shp

where:

<YYYYMMDD> is the release date of the dataset

<ZONECODE> is the mnemonic for each ceremonial county data distribution zone covered by the shapefile (see Table 1).

Each shapefile will be accompanied by a metadata xml file in the accordance to the UK GEMINI v 2.2 standard.

Please note that the final packaged filenames (see Table 1) may be different due to other requirements.

6 Thematic Accuracy

Thematic accuracy is concerned with the degree to which the classification and attribution of features correctly match the real world features that are being modelled within the dataset.

The quality of CROME land code classification was assessed by comparing the crop/land use types predicted by the Random Forest Classification against the ground truth data collated by the field inspectors from Rural Payments Agency. The comparison is reported in the form of a confusion matrix, with the overall accuracy and Kappa Coefficient presented in Table 3 below. The confusion matrix was measured on the majority of CROME cells within each RPA land parcel. CROME v2018.2 has an overall accuracy of 81% and a Kappa coefficient of 0.8, which confirms that a high quality of land use classification is achievable with Sentinel-1 radar data, complimented with Sentinel-2 for distinguishing grass/rough surfaces. The overall accuracy while looks superficially lower than previous years, it would be evident from Table 4 that individual crop accuracies are good.

The Ground Truth data didn't provide information on non-agricultural land covers such as Woodland, water bodies and general non-agricultural areas (e.g. manmade surfaces) therefore the confusion matrix doesn't provide accuracy numbers for each land use. Samples for these land uses were collected from other reliable sources e.g. non-Remote Sensing inspections, and were only used during the training to minimise confusion with similar classes.

6.1 Known Accuracy Challenges

Due to strong correspondence in the physical morphology of Permanent Crops ground truths and other trees, TC01 cells also cover areas of other trees e.g. along parcel boundaries, roads. Due to lack of any definitive morphological definition for fallow land ground truth in general, FA01 cells also cover areas that are mostly bare soil to partially grass. Similarly, due to variability in growth of grass, PG01 cells cover areas that are declared as fallow land by the customers. The seasonality of the suitable Sentinel-2 image used for cleansing can also influence the attribution of an otherwise vegetated parcels to NA01 if the usable image was taken when the field had been harvested or still bare soil.

7 Dataset Specification

7.1 Format

The CROME datasets are in ESRI shapefile format.

7.2 Topological Consistency

No topological consistency errors are known to exist with CROME, i.e. each feature is valid according to the OGC specification.

7.3 Horizontal Positional Accuracy

Not applicable

7.4 Currency

The map is to be updated annually, after August to coincide approximately with end of harvesting and cropping season.

7.5 Format Consistency

N/A

7.6 Domain Consistency

N/A

7.7 Temporal Consistency

There are no known temporal consistency issues with CROME.

7.8 Temporal Validity

There are no known temporal validity issues with CROME.

7.9 Attribute Completeness

The version of the dataset has 100% attribute completeness.

7.10 Spatial Completeness

The version of the dataset has 100% spatial completeness, as verified by visual inspection.

7.11 Lineage

Crop types were derived by using Random Forest Classification on Sentinel-1 Radar data, and refined using vegetation indices from Sentinel-2 optical data.

7.12 CROME Layer Metadata

A metadata file will be supplied with each product supply. Metadata will conform to ISO 19115 and be UK GEMINI discovery level metadata.

		Ground Truth																											
		AC01	AC03	AC07	AC15	AC16	AC17	AC19	AC30	AC32	AC34	AC44	AC58	AC59	AC63	AC65	AC66	AC67	AC68	AC69	FA01	LG03	LG07	LG11	LG14	LG20	PG01	WO12	Total
CROME	AC01	524	4	0	0	11	5	15	3	29	1	0	3	0	15	0	9	0	0	0	42	0	0	1	0	0	1	1	664
	AC03	0	70	0	0	0	0	0	0	0	3	0	0	0	1	0	0	0	0	0	1	0	0	0	0	0	0	0	75
	AC07	0	0	2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	2
	AC15	0	0	0	4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	4
	AC16	0	0	0	0	31	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	32
	AC17	11	15	0	3	1	444	8	0	14	2	6	28	0	1	1	3	0	0	0	82	3	0	4	1	1	8	0	636
	AC19	25	0	0	1	15	2	351	1	33	0	0	2	0	2	2	7	0	1	0	23	0	0	0	0	1	5	0	471
	AC30	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	AC32	6	0	0	0	1	1	5	0	124	0	0	0	0	0	0	6	0	0	0	1	0	0	0	0	0	3	0	147
	AC34	0	0	0	0	0	0	0	0	0	10	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	11
	AC44	1	9	0	0	0	4	0	0	0	7	127	2	0	0	0	0	0	0	0	8	0	0	1	0	0	1	0	160
	AC58	0	0	0	0	0	0	0	0	0	0	0	5	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	5
	AC59	0	0	0	0	0	0	0	0	0	0	0	0	2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	2
	AC63	6	0	0	0	0	2	0	0	0	0	0	3	2	452	0	5	2	2	0	19	0	0	0	1	0	7	0	501
	AC65	1	0	0	0	0	1	2	0	0	0	0	0	0	1	267	1	0	0	0	6	0	0	0	0	0	0	0	279
	AC66	4	0	0	0	0	3	1	0	19	0	0	7	3	0	7	850	1	0	0	43	0	0	1	0	2	4	0	945
	AC67	1	0	0	0	0	3	0	0	0	0	0	4	1	1	0	3	467	0	0	10	0	0	0	0	0	4	1	495
	AC68	0	0	0	0	0	0	0	0	0	0	0	0	0	2	0	0	0	35	0	1	0	0	0	0	0	0	0	38
	AC69	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	4	0	0	0	0	0	0	0	0	4
	FA01	7	6	2	9	13	17	4	0	2	2	2	15	1	1	0	0	0	0	0	283	2	1	9	0	0	12	0	388
	LG03	6	1	0	0	1	5	1	0	1	1	0	5	1	0	0	0	1	0	0	26	178	7	0	0	6	3	0	243
	LG07	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	38	0	0	0	0	0	39
	LG11	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	30	0	0	0	0	30
	LG14	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	13	0	0	0	13
	LG20	1	0	0	0	0	1	0	0	0	1	0	2	0	1	0	1	2	0	0	18	2	3	0	0	164	7	1	204
	PG01	0	0	0	0	0	1	0	0	0	0	0	13	4	1	1	2	1	0	0	120	0	0	15	19	0	565	1	743
WO12	2	0	0	0	0	3	1	0	1	0	0	13	2	0	1	1	0	0	0	57	1	0	0	0	1	23	8	114	
Total	595	105	4	17	73	492	388	4	223	27	136	102	16	478	279	888	474	38	4	742	186	49	61	34	175	643	12	6245	

Table 3. Confusion Matrix of CROME v 2018.2

Land Cover	Accuracy	
	User	Producer
Spring Barley	79%	88%
Beet	93%	67%
Carrot	100%	50%
Lettuce	100%	24%
Spring Linseed	97%	42%
Maize	70%	90%
Spring Oats	75%	90%
Spring Wheat	84%	56%
Spring Cabbage	91%	37%
Potato	79%	93%
Mixed Crops	100%	5%
Mixed Crops	100%	13%
Winter Barley	90%	95%
Winter Oats	96%	96%
Winter Wheat	90%	96%
Winter Oilseed	94%	99%
Winter Rye	92%	92%
Winter Triticale	100%	100%
Fallow	73%	38%
Spring Field Beans	73%	96%
Spring Peas	97%	78%
Lucerne	100%	49%
Clover	100%	38%
Winter Field Beans	80%	94%
Grass	76%	88%
Trees	7%	67%

Table 4. User and Producer accuracies of land cover.

Annex A – Land Cover Codes

Land Cover Description	LUCODE	Land Use Description
Cereal Crops	AC01	Spring Barley
	AC03	Beet
	AC04	Borage
	AC05	Buckwheat
	AC06	Canary Seed
	AC07	Carrot
	AC09	Chicory
	AC10	Daffodil
	AC14	Hemp
	AC15	Lettuce
	AC16	Spring Linseed
	AC17	Maize
	AC18	Millet
	AC19	Spring Oats
	AC20	Onions
	AC22	Parsley
	AC23	Parsnips
	AC24	Spring Rye
	AC26	Spinach
	AC27	Strawberry
	AC30	Spring Triticale
	AC32	Spring Wheat
	AC34	Spring Cabbage
	AC35	Turnip
	AC36	Spring Oilseed
	AC37	Brown Mustard
	AC38	Mustard
	AC41	Radish
	AC44	Potato
	AC45	Tomato
	AC50	Squash
	AC52	Siam Pumpkin
	AC58	Mixed Crop-Group 1
	AC59	Mixed Crop-Group 2
	AC60	Mixed Crop-Group 3
	AC61	Mixed Crop-Group 4
	AC62	Mixed Crop-Group 5
	AC63	Winter Barley
	AC64	Winter Linseed
	AC65	Winter Oats
	AC66	Winter Wheat
	AC67	Winter Oilseed
	AC68	Winter Rye
	AC69	Winter Triticale
	AC70	Winter Cabbage
	AC71	Coriander
	AC72	Corn gromwell
	AC74	Phacelia
	AC81	Poppy
	AC88	Sunflower
AC90	Gladioli	
AC92	Sorghum	
AC94	Sweet William	
AC100	Italian Ryegrass	



	CA02	Cover Crop
Leguminous Crops	LG01	Chickpea
	LG02	Fenugreek
	LG03	Spring Field beans
	LG04	Green Beans
	LG06	Lupins
	LG07	Spring Peas
	LG09	Cowpea
	LG08	Soya
	LG11	Lucerne
	LG13	Sainfoin
	LG14	Clover
	LG15	Mixed Crops–Group 1 Leguminous
	LG16	Mixed Crops–Group 2 Leguminous
	LG20	Winter Field beans
	LG21	Winter Peas
Energy Crop	SR01	Short Rotation Coppice
Grassland	FA01	Fallow Land
	HE02	Heathland and Bracken
	PG01	Grass
Non–Agricultural Land	NA01	Non-vegetated or sparsely-vegetated Land
Water	WA01	Water
Trees	TC01	Perennial Crops and Isolated Trees
	NU01	Nursery Crops
	WO12	Trees and Scrubs, short Woody plants, hedgerows
Unknown Vegetation Or Mixed Vegetation	AC00	Unknown or Mixed Vegetation

Note that the variety of land cover codes may change during releases of CROME due to variability in ground truth however the LUCODE will remain same.

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